

PERHITUNGAN EFISIENSI MESIN LENOIR KLASIK DAN KUANTUM

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1 → 2 (isokorik):  $\frac{P_1 V_1}{T_1} = \frac{P_2 V_2}{T_2}$   
 $Q_{12} = m c_v (T_2 - T_1)$   
 $W_{12} = \int_1^2 P dV = 0$   
 $\frac{T_2}{T_1} = \frac{P_2}{P_1} > 1$

2 → 3 (isotropik atau adiabatik reversibel):  
 $Q_{23} = 0$   
 $W_{23} = -\Delta U_{23}$   
 $= -\int_2^3 dU$   
 $= -m c_v \int_{T_2}^{T_3} dT$   
 $= m c_v (T_2 - T_3)$

3 → 1 (kompresi isobar):  
 $Q_{31} = m c_p (T_1 - T_3) = -m c_p (T_3 - T_1)$   
 $\Delta U_{31} = \int_3^1 dU$   
 $= m c_v \int_{T_3}^{T_1} dT$   
 $= m c_v (T_1 - T_3), T_3 > T_1$   
 $\frac{P_1 V_1}{T_1} = \frac{P_3 V_3}{T_3} \Leftrightarrow \frac{T_1}{T_3} = \frac{V_1}{V_3} < 1$

$W_{31} = Q_{31} - \Delta U_{31}$   
 $= m c_p (T_1 - T_3) - m c_v (T_1 - T_3)$   
 $= m (c_p - c_v) (T_1 - T_3), T_3 > T_1$

Cari  $W_{total}$ :  
 $W_{total} = W_{12} + W_{23} + W_{31}$   
 $= 0 + m c_v (T_2 - T_3) + m (c_p - c_v) (T_1 - T_3)$   
 $= m c_v T_2 - m c_v T_3 + m (c_p T_1 - c_p T_3 - c_v T_1 + c_v T_3)$   
 $= m c_v T_2 - m c_v T_3 + m c_p T_1 - m c_p T_3 - m c_v T_1 + m c_v T_3$   
 $= m c_v (T_2 - T_1) + m c_p (T_1 - T_3)$

atau  
 $W_{total} = |Q_{12}| - |Q_{31}|$   
 $= m c_v (T_2 - T_1) - m c_p (T_3 - T_1)$   
 $= m c_v (T_2 - T_1) - m c_p (T_3 - T_1)$

Cari  $\eta$ :  
 $\eta = \frac{W_{total}}{Q_{12}} = \frac{m c_v (T_2 - T_1) - m c_p (T_3 - T_1)}{m c_v (T_2 - T_1)}$   
 $= 1 - \frac{c_p (T_3 - T_1)}{c_v (T_2 - T_1)}$

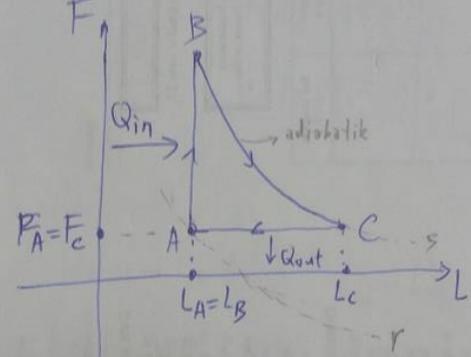
dengan  $\gamma = \frac{c_p}{c_v}, r = \frac{P_2}{P_1}$   
 $\frac{P_1}{T_1} = \frac{P_2}{T_2} \Leftrightarrow T_2 = \frac{P_2}{P_1} T_1 = r T_1$   
 $\frac{T_2}{T_3} = \left(\frac{P_2}{P_3}\right)^{\frac{\gamma-1}{\gamma}} = \left(\frac{P_2}{P_1}\right)^{\frac{\gamma-1}{\gamma}} = r^{1-\frac{1}{\gamma}}$   
 $\Leftrightarrow T_3 = T_2 r^{\frac{1}{\gamma}} = (r T_1) r^{\frac{1}{\gamma}} = T_1 r^{\frac{\gamma+1}{\gamma}}$

atau  $\eta = \frac{W_{total}}{Q_{in}} = \frac{Q_{in} - Q_{out}}{Q_{in}} = 1 - \frac{|Q_{out}|}{|Q_{in}|} = 1 - \frac{Q_{31}}{Q_{12}} = 1 - \frac{m c_p (T_3 - T_1)}{m c_v (T_2 - T_1)}$

$$\begin{aligned}
 1 &= 1 - \gamma \frac{T_1 r^{\frac{1}{\gamma}} - T_1}{T_1 r - T_1} \\
 &= 1 - \gamma \frac{T_1 (r^{\frac{1}{\gamma}} - 1)}{T_1 (r - 1)} \\
 &= 1 - \gamma \frac{r^{1/\gamma} - 1}{r - 1} \\
 &= 1 - \gamma \frac{\left(\frac{V_2}{V_1}\right)^{\gamma} - 1}{\left(\frac{V_2}{V_1}\right)^{\gamma} - 1}
 \end{aligned}$$

$$\begin{aligned}
 P_2 V_2^\gamma &= P_3 V_3^\gamma \\
 P_2 &= \left(\frac{V_3}{V_2}\right)^\gamma P_3 \\
 &= \left(\frac{V_2}{V_1}\right)^\gamma P_1 \\
 r &= P_2/P_1 \\
 &= \left(\frac{V_2}{V_1}\right)^\gamma
 \end{aligned}$$

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A → B (isokhorik):

transisi keadaan  $r \rightarrow s$

$$\Psi_{AB}(x) = a_r \phi_r + a_s \phi_s$$

$$\begin{aligned}
 \Delta U_{AB} &= E_B - E_A \\
 &= \frac{s^2 \pi^2 \hbar^2}{2mL_B^2} - \frac{r^2 \pi^2 \hbar^2}{2mL_A^2} \\
 &= \frac{s^2 \pi^2 \hbar^2}{2mL_A^2} - \frac{r^2 \pi^2 \hbar^2}{2mL_A^2} \\
 &= (s^2 - r^2) \frac{\pi^2 \hbar^2}{2mL_A^2}
 \end{aligned}$$

$$W_{AB} = 0$$

B → C (ekspansi adiabatik reversibel):  
tidak mengubah probabilitas kehadiran partikel

$$\Psi_{BC} = \phi_s$$

$$E_{BC} = \frac{s^2 \pi^2 \hbar^2}{2mL^2}$$

$$F_{BC} = \frac{s^2 \pi^2 \hbar^2}{mL^3}$$

$$\begin{aligned}
 W_{BC} &= \int_{L_B}^{L_C} F_{BC} dL \\
 &= \frac{s^2 \pi^2 \hbar^2}{m} \int_{L_B}^{L_C} \frac{1}{L^3} dL \\
 &= \frac{s^2 \pi^2 \hbar^2}{m} \left[ \frac{L^{-2}}{-2} \right]_{L_B}^{L_C} \\
 &= \frac{s^2 \pi^2 \hbar^2}{-2m} \left( \frac{1}{L_C^2} - \frac{1}{L_B^2} \right) \\
 &= \frac{s^2 \pi^2 \hbar^2}{2m} \left( \frac{1}{L_B^2} - \frac{1}{L_C^2} \right) \\
 &= \frac{s^2 \pi^2 \hbar^2}{2m} \left( \frac{1}{L_A^2} - \frac{1}{L_C^2} \right)
 \end{aligned}$$

C → A (kompresi isobar):

transisi keadaan  $s \rightarrow r$

$$\Psi_{CA}(x) = a_r \phi_r + a_s \phi_s$$

$$|\psi_{CA}\rangle = a_r |r\rangle + a_s |s\rangle$$

Syarat normalisasi:

$$\begin{aligned}
 1 &= \langle CA | CA \rangle \\
 &= (a_r^* \langle r| + a_s^* \langle s|) (a_r |r\rangle + a_s |s\rangle) \\
 &= a_r^* a_r \langle r|r\rangle + a_s^* a_s \langle s|s\rangle \\
 &= |a_r|^2 + |a_s|^2
 \end{aligned}$$

$$|a_s|^2 = 1 - |a_r|^2$$

maka gaya mekanik yang bekerja

$$F_{CA}(L) = \left[ |dr|^2 r^2 + |ds|^2 s^2 \right] \frac{\pi^2 \hbar^2}{mL^3}$$

$$= \left[ |dr|^2 r^2 + (1 - |dr|^2) s^2 \right] \frac{\pi^2 \hbar^2}{mL^3}$$

$$= \left[ s^2 + |dr|^2 (r^2 - s^2) \right] \frac{\pi^2 \hbar^2}{mL^3}$$

Pada proses isobar kuantum berlaku

$$F_C = F_{CA}$$

$$\frac{s^2 \pi^2 \hbar^2}{mL^3} = \left[ s^2 + |dr|^2 (r^2 - s^2) \right] \frac{\pi^2 \hbar^2}{mL^3}$$

$$s^2 \frac{L^3}{L^3} = \left[ s^2 + |dr|^2 (r^2 - s^2) \right]$$

$$L = \left[ \frac{s^2 + |dr|^2 (r^2 - s^2)}{s^2} \right]^{1/3} L_C$$

$$|dr|=0 \rightarrow L = L_C$$

$$|dr|=1 \rightarrow L = \left( \frac{r}{s} \right)^{2/3} L_C = L_A, s > r$$

$$F_{CA}(L) = \frac{s^2 L^3}{L^3} \frac{\pi^2 \hbar^2}{mL^3} = \frac{s^2 \pi^2 \hbar^2}{mL_C^3} = \text{konstan}$$

$$= F_C = F_A$$

$$W_{CA} = \int_{L_C}^{L_A} F_{CA} dL$$

$$= \int_{L_C}^{L_A} \frac{s^2 \pi^2 \hbar^2}{mL_C^3} dL$$

$$= \frac{s^2 \pi^2 \hbar^2}{mL_C^3} \int_{L_C}^{L_A} dL$$

$$= \frac{s^2 \pi^2 \hbar^2}{mL_C^3} [L]_{L_C}^{L_A}$$

$$W_{CA} = \frac{s^2 \pi^2 \hbar^2}{mL_C^3} (L_A - L_C)$$

$$= \frac{s^2 \pi^2 \hbar^2}{mL_C^3} \left[ \left( \frac{r}{s} \right)^{2/3} L_C - L_C \right]$$

$$= \frac{s^2 \pi^2 \hbar^2}{mL_C^3} \left[ \left( \frac{r}{s} \right)^{2/3} - 1 \right] L_C$$

$$= \frac{r^{2/3} s^{4/3} \pi^2 \hbar^2}{mL_C^2} - \frac{s^2 \pi^2 \hbar^2}{mL_C^2}$$

Cari  $W_{tot}$ :

$$W_{tot} = W_{AB} + W_{BC} + W_{CA}$$

$$= 0 + \left( \frac{s^2 \pi^2 \hbar^2}{2mL_A^2} - \frac{s^2 \pi^2 \hbar^2}{2mL_C^2} \right)$$

$$+ \left( \frac{r^{2/3} s^{4/3} \pi^2 \hbar^2}{mL_C^2} - \frac{s^2 \pi^2 \hbar^2}{mL_C^2} \right)$$

$$= \frac{s^2 \pi^2 \hbar^2}{2mL_C^2} - \frac{3s^2 \pi^2 \hbar^2}{2mL_C^2} + \frac{r^{2/3} s^{4/3} \pi^2 \hbar^2}{mL_C^2}$$

Cari  $Q_{in}$ :

$$Q_{in} = Q_{AB}$$

$$= \Delta U_{AB} + W_{AB}$$

$$= (s^2 - r^2) \frac{\pi^2 \hbar^2}{2mL_A^2} + 0$$

$$= (s^2 - r^2) \frac{\pi^2 \hbar^2}{2m} \cdot \frac{1}{\left[ \left( \frac{r}{s} \right)^{2/3} L_C \right]^2}$$

$$= (s^2 - r^2) \left( \frac{s}{r} \right)^{4/3} \frac{\pi^2 \hbar^2}{2mL_C^2}$$

$$= \left( s^{10/3} r^{-4/3} - s^{4/3} r^{2/3} \right) \frac{\pi^2 \hbar^2}{2mL_C^2}$$

$$\begin{aligned}
 W_E &= W_{AB} + W_{BC} + W_{CA} \\
 &= 0 + \left( \frac{s^2 \pi^2 h^2}{2mL_A^2} - \frac{s^2 \pi^2 h^2}{2mL_C^2} \right) \\
 &\quad + \frac{r^{2/3} s^{4/3} \pi^2 h^2}{mL_C^2} - \frac{s^2 \pi^2 h^2}{mL_C^2} \\
 &= \frac{s^2 \pi^2 h^2}{2m} \cdot \frac{1}{\left(\frac{r}{s}\right)^{4/3} L_C^2} - \frac{s^2 \pi^2 h^2}{2mL_C^2} \\
 &\quad + \frac{r^{2/3} s^{4/3} \pi^2 h^2}{mL_C^2} - \frac{s^2 \pi^2 h^2}{mL_C^2} \cdot \frac{2}{2} \\
 &= \frac{s^2 \left(\frac{s}{r}\right)^{4/3} \pi^2 h^2}{2mL_C^2} - \frac{3s^2 \pi^2 h^2}{2mL_C^2} \\
 &\quad + \frac{r^{2/3} s^{4/3} \pi^2 h^2}{mL_C^2} \cdot \frac{2}{2} \\
 &= \left[ s^2 \left(\frac{s}{r}\right)^{4/3} - 3s^2 + 2r^{2/3} s^{4/3} \right] \frac{\pi^2 h^2}{2mL_C^2} \\
 &= \left[ s^2 \left(\frac{s}{r}\right)^{4/3} + 2r^{2/3} r^{-4/3} s^{4/3} - 3s^2 \right] \frac{\pi^2 h^2}{2mL_C^2} \\
 &= \left[ s^2 \left(\frac{s}{r}\right)^{4/3} + 2r^2 \left(\frac{s}{r}\right)^{4/3} - 3s^2 \right] \frac{\pi^2 h^2}{2mL_C^2} \\
 &= \left[ s^2 \left(\frac{s}{r}\right)^{4/3} - r^2 \left(\frac{s}{r}\right)^{4/3} + 3r^2 \left(\frac{s}{r}\right)^{4/3} - 3s^2 \right] \frac{\pi^2 h^2}{2mL_C^2} \\
 &= \left[ (s^2 - r^2) \left(\frac{s}{r}\right)^{4/3} + 3 \left[ r^2 \left(\frac{s}{r}\right)^{4/3} - s^2 \right] \right] \frac{\pi^2 h^2}{2mL_C^2} \\
 &= \frac{1}{2} (s^2 - r^2) \left(\frac{s}{r}\right)^{4/3} - 3 \left[ s^2 - r^2 \left(\frac{s}{r}\right)^{4/3} \right] \frac{\pi^2 h^2}{2mL_C^2}
 \end{aligned}$$

maka

$$\begin{aligned}
 \eta &= \frac{W_E}{Q_{in}} \\
 &= \frac{\frac{1}{2} (s^2 - r^2) \left(\frac{s}{r}\right)^{4/3} - 3 \left[ s^2 - r^2 \left(\frac{s}{r}\right)^{4/3} \right] \frac{\pi^2 h^2}{2mL_C^2}}{(s^2 - r^2) \left(\frac{s}{r}\right)^{4/3} \frac{\pi^2 h^2}{2mL_C^2}} \\
 &= 1 - 3 \frac{\left[ s^2 - r^2 \left(\frac{s}{r}\right)^{4/3} \right]}{(s^2 - r^2) \left(\frac{s}{r}\right)^{4/3}} \\
 &= 1 - 3 \frac{s^2 \left(\frac{s}{r}\right)^{4/3} - r^2 \left(\frac{s}{r}\right)^{4/3}}{s^2 \left(\frac{s}{r}\right)^{4/3} - r^2 \left(\frac{s}{r}\right)^{4/3}}
 \end{aligned}$$

$$\begin{aligned}
 \eta &= 1 - 3 \frac{r^2 \left[ \left(\frac{s}{r}\right)^{4/3} - 1 \right]}{s^2 - r^2} \\
 &= 1 - 3 \frac{r^2 \left[ \left(\frac{s}{r}\right)^{2 \cdot 2/3} - 1 \right]}{s^2 - r^2} \\
 &= 1 - 3 \frac{r^2 \left[ \left(\frac{s}{r}\right)^{2/3} - 1 \right]}{s^2 - r^2} \cdot \frac{1/r^2}{1/r^2} \\
 &= 1 - 3 \frac{\left(\frac{s}{r}\right)^{2/3} - 1}{\left(\frac{s}{r}\right)^2 - 1}
 \end{aligned}$$

dengan

$$\begin{aligned}
 \left(\frac{r}{s}\right)^{2/3} &= \frac{L_A}{L_C} \\
 \frac{r}{s} &= \left(\frac{L_A}{L_C}\right)^{3/2} \\
 \frac{s}{r} &= \left(\frac{L_C}{L_A}\right)^{3/2}
 \end{aligned}$$

$$\begin{aligned}
 \eta &= 1 - 3 \frac{\left[ \left(\frac{L_C}{L_A}\right)^{3/2} \right]^{2/3} - 1}{\left[ \left(\frac{L_C}{L_A}\right)^{3/2} \right]^2 - 1} \\
 &= 1 - 3 \frac{\left(\frac{L_C}{L_A}\right) - 1}{\left(\frac{L_C}{L_A}\right)^3 - 1} \\
 &= 1 - \delta \frac{r - 1}{r^3 - 1}
 \end{aligned}$$

dengan  $\delta = 3$

$$r = \frac{L_C}{L_A}$$